

Applied Math Preliminary Exam: Linear Algebra

University of California, Merced, January 2022

Instructions: This examination lasts 4 hours. Each problem is worth 20 points. While there are 8 problems, your total score will be calculated by adding up your 6 highest scores. Hence, the maximum total score is $6 \times 20 = 120$ points. Show explicitly the steps and calculations in your solutions. Credit will not be given to answers without explanation. Partial credit will be awarded for relevant work.

1. (a) By solving $A\mathbf{x} = \mathbf{0}$, find a basis for the null space of A

$$A = \begin{bmatrix} 1 & 0 & 2 & 2 \\ 0 & 1 & 1 & 1 \end{bmatrix}. \quad (1)$$

- (b) For $\mathbf{u} = [1 \ 0 \ 2 \ 2]$ and $\mathbf{v} = [0 \ 1 \ 1 \ 1]$, let S be the linear subspace of \mathbb{R}^4 spanned by \mathbf{u} and \mathbf{v} (i.e. $S = \text{Span}\{\mathbf{u}, \mathbf{v}\}$). Find a basis for the orthogonal complement S^\perp of S .

2. In your TA discussion, where you review how to compute the eigenvalues and eigenvectors of a square matrix, you use the following two 2×2 matrices:

$$X = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix}, \quad Y = \begin{bmatrix} 1 & -1 \\ 1 & 3 \end{bmatrix}. \quad (2)$$

Based on the results for X and Y , a student comes up with the following conjecture: *for any real $n \times n$ matrix, (1) all eigenvalues are real and (2) n linearly independent eigenvectors can be found.*

- (a) Find a counterexample to each part of the conjecture.
(b) Can you give a correct statement for some class of matrices?

3. Let R be a rotation matrix

$$R = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}, \quad \theta \in \mathbb{R}. \quad (3)$$

- (a) Express the following quantities in terms of θ :

- the 1-norm $\|R\|_1$ of R ,
- the ∞ -norm $\|R\|_\infty$ of R ,
- the 2-norm $\|R\|_2$ of R ,
- the spectral radius $\rho(R)$ of R .

- (b) Compare the magnitudes of $\|R\|_1$, $\|R\|_\infty$, $\|R\|_2$, and $\rho(R)$.

4. We want to solve the following linear recurrence relation using eigenvalues and eigenvectors:

$$a_{n+2} = 6a_{n+1} - 8a_n \quad \text{with } a_1 = 1 \text{ and } a_2 = 4. \quad (4)$$

- (a) Find A satisfying

$$\mathbf{x}_{n+1} = A\mathbf{x}_n, \quad \text{where } \mathbf{x} = \begin{bmatrix} a_{n+1} \\ a_n \end{bmatrix}. \quad (5)$$

- (b) Diagonalize $A = PDP^{-1}$.

- (c) Using $\mathbf{x}_{n+1} = A^n \mathbf{x}_1$, express a_n in terms of n .

5.

$$P = \begin{bmatrix} \frac{1}{3} & -\frac{1}{3} & \frac{1}{3} \\ -\frac{1}{3} & \frac{1}{3} & -\frac{1}{3} \\ \frac{1}{3} & -\frac{1}{3} & \frac{1}{3} \end{bmatrix}. \quad (6)$$

- (a) Express P as $P = \mathbf{v}\mathbf{v}^T$ for a vector \mathbf{v} .
- (b) Can you give a physical interpretation of P as a linear transformation $\mathbb{R}^3 \rightarrow \mathbb{R}^3: \mathbf{x} \mapsto P\mathbf{x}$?
- (c) What is P^{100} ? (Hint: Use the result of either (a) or (b))
- (d) What is the rank of P ?
- (e) Find a vector \mathbf{u} such that \mathbf{u} is orthogonal to the null space of P .

6. The singular value decomposition of A is given as follows:

$$A = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 3 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} = U\Sigma V^T. \quad (7)$$

- (a) What is the rank of A ?
- (b) Write down an orthonormal basis of the range space of A .
- (c) Write down an orthonormal basis of the null space of A .
- (d) Can we obtain other singular value decompositions of A using

$$\bar{U} = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad \text{or} \quad \tilde{U} = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix} \quad (8)$$

instead of U ? If so, what kind of changes are needed for Σ or V in each case?

7. We want to find the *best* linear fit to the following points:

$$\{(-1, 0), (0, 0), (0, 1), (1, 2)\}. \quad (9)$$

- (a) By constructing a normal system, find the least-squares fit $y = ax + b$.
- (b) Plot the best linear fit with the data points.
- (c) Briefly explain in which sense the least-squares fit is optimal.

8. Consider the three vectors

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 3 \\ 0 \\ 3 \\ 0 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 5 \\ 3 \\ 1 \\ -1 \end{bmatrix}. \quad (10)$$

- (a) Perform the Gram-Schmidt process to find an orthonormal basis $\{\mathbf{q}_1, \mathbf{q}_2, \mathbf{q}_3\}$ for the subspace spanned by $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$.
- (b) Using the result of (a), find the following decomposition

$$[\mathbf{v}_1 \quad \mathbf{v}_2 \quad \mathbf{v}_3] = [\mathbf{q}_1 \quad \mathbf{q}_2 \quad \mathbf{q}_3] \begin{bmatrix} r_{11} & r_{12} & r_{13} \\ 0 & r_{22} & r_{23} \\ 0 & 0 & r_{33} \end{bmatrix}. \quad (11)$$